PRESENTATION

BEAM PROFILING CAMERA



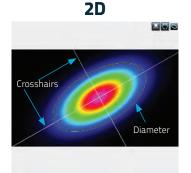
See page 172

BEAMAGE-3.0

- Up to 10X faster than regular USB 2.0 connections
- 2.2 MPixels resolution gives accurate profile measurements on very small beams
- 11.3 x 6.0 mm sensor allows to measure very large beams
- **ISO Compliant**: D4σ Definition of Diameter, Centroid, Ellipticity and Orientation are ISO 11146:2004 and 11146:2005 compliant
- Easy to navigate interface, with many display and control features
- External Trigger to synchronize the camera with a pulsed laser
- The most affordable, large size camera-based beam profiler on the market!



2D, 3D AND XY DISPLAYS



The 2D display features the crosshairs (set to the major and minor axis or along specified angles) and the measured diameter of the beam. This diameter varies with the chosen definition (4-sigma, FWHM, 1/e², etc.) and its display can be turned ON or OFF.

SUBTRACT

The background subtraction function

is a necessary tool to have an accurate

measurement and to abide by the ISO-11146-3:2004 standards. Contamination

of environment noise subtraction.

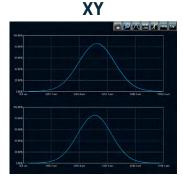
of all images can be avoided with the help

BACKGROUND

MAIN FUNCTIONS

3D - -

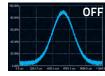
The 3D display shows the actual shape of the beam. It is possible to easily zoom, pan and rotate the data. The very useful Reset button allows to put the data back in its original configuration.



The XY display plots cross-sectional graphs of the beam along the crosshairs. This display features many useful tools, like zoom, cursor, and FWHM and 1/e² level bars. It is also possible to display the graphs in semi-log format.



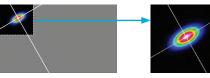
Filter out the noise in your beam profile by using this spatial filter function. This tool is great for low quality lasers or low level signals.







Increase the data transfer rate by reducing the area of the sensor that is scanned



MONITORS

ENERGY DETECTORS

POWER DETECTORS

HIGH POWER DETECTORS

PRESENTATION

REAL-TIME M2 MODULE (Available Fall 2013)



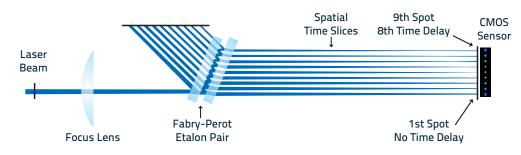
See page 178

Measurements are done using a completely passive optical approach. The heart of the Beamage-M2 is a Fabry-Perot interferometer that creates time delayed slices of the beam. After these slices have landed on the sensor, each one a spatial cross section along the waist, the software simultaneously tracks and analyzes them.

BEAMAGE-M2

- Instant Measurement: the Fabry-Perot optics allow the M2 factor measurement in less than a second with no moving parts
- ISO Compliant
- Built -In Attenuation: OD4 attenuation provided by the Fabry-Perot optics itself and optional removable attenuators are available for attenuation up to OD7
- Modular: The Beamage-3.0 camera can be used separately from the M2 module for needs of spatial intensity or energy profiling
- Complete Software: Easy-to-use with an array of useful functions and tools

THE FABRY-PEROT INTERFEROMETER



INTUITIVE SOFTWARE

The M² measurements are taken directly in our PC-Beamage-3.0 software. An easy stepby-step procedure is clearly indicated directly in the software and allows the user to get the fastest M² measurement available. The ISO calculations give M² values in both the X and Y axes. The M² measures are taken at a rate of 3 fps. The system also automatically detects the multiple beams, allowing for an easy setup. Once the system is calibrated, you can take as many measurements as you like, without moving any parts or modifying parameters.



DIFFRACTIVE OPTICS



See page 182

HBS Series

- Online Monitoring: Do real-time sampling of your laser and measure your profile while working
- Saptial Profile Preserved: The HBS will not create artefacts in your measurements or in your main beam
- Environment Insensitive: The ONLY sampling component that is trully insensitive to ALL environmental variations, including polarization and vibrations
- Very High Damage Threshold: The damage threshold of the HBS Series can be as high as that of fused silica



Pixel

Addressing

178

186

188

UV Converters & **IR** Adaptors

Pelican Carrying Case

MONITORS

THZ DETECTORS

DEM DETECTORS

BEAMAGE-3.0 SPECIFICATIONS

| SENSOR TECHNOLOGY | CMOS |
|--------------------------------|---|
| EFFECTIVE APERTURE | 11.3 x 6.0 mm |
| | |
| MEASUREMENT CAPABILITY | |
| Wavelength Range | 350 - 1150 nm |
| Pixel Count | 2.2 MPixels |
| H x V | 2048 x 1088 |
| Pixel Dimension | 5.5 x 5.5 μm |
| Minimum Measurable Beam | ~55 µm |
| Shutter Type | Global |
| Frame Rate (at 1 MPixels) | 10 fps |
| RMS Noise | 1000:1 (60 dB) |
| ADC Level (User Setable) | 12 bit (default) / 10 bit (option) |
| M2 Measurement | In Real-Time, no moving parts, with the Beamage-M2 Module* (see page 178) |
| DAMAGE THRESHOLDS ^a | |
| Maximum Average Power | 1 W |
| Saturation Level (1064 nm) | CW: 10 W/cm ² ; Pulsed: 300 µJ/cm ² |
| SOFTWARE | |
| Displays | 2D, 3D and XY |
| Display Features | 2D: Print Screen, Reset View, Show/Hide Beam Diameter |
| | 3D: Print Screen, Reset View, Top View |
| | XY: Save Data, Zoom, Gaussian Fit, Semi-Log, Show/Hide Cursor, Show/Hide FWHM, Show/Hide 1/e ² |
| Beam Diameter Definitions | D4σ (ISO compliant) |
| | 1/e² along crosshairs (13.5%) |
| | |

BEAMAGE-3.0

FWHM along crosshairs (50%)

86% effective diameter (D86)

Open File, Save Current Data, Save All Data, Previous/Next Image, Clear Buffer, Animate

Full Report in Print Ready Format (2D, 3D, XY, Measures, Parameters) Print Screen in BMP format (2D and 3D)

11.3 x 6.0 mm

0.67 cm²

61H x 81.1W x 19.7D mm

139 g

Beamage-3.0

201939 •

Buffer Controls Printing and Reports

MODEL

PHYSICAL CHARACTERISTICS

Sensor Size Sensor Area Dimensions (not including filter) Weight (head only)

ORDERING INFORMATION

Full Product Name Product Number (Stand not included)

a. With ND4 filter.
b. Available for order now, deliveries start in April 2013. Ask your Gentec-EO representative for pricing.
* Available Fall 2013.

Specifications are subject to change without notice

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WEEE/Rot



MONITORS

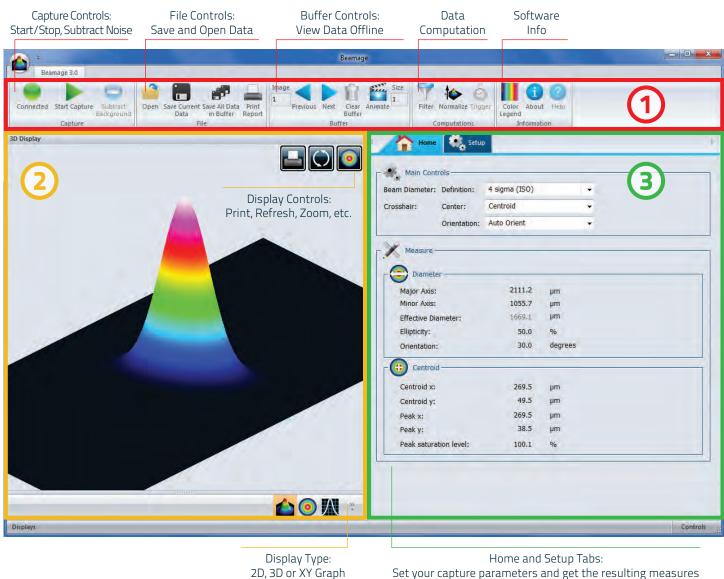
ENERGY DETECTORS

POWER DETECTORS

HIGH POWER DETECTORS

BEAMAGE-3.0

INTUITIVE SOFTWARE INTERFACE



MAIN CONTROLS

The top portion of the software is in a ribbon format and includes all the main controls. These are grouped by family, including capture controls, file controls, buffer controls and data computations such as a very useful spatial filter and a normalizing function.

DISPLAYS

The left-hand side of the software is the display panel. 3 displays are available: 3D, 2D and XY (cross-sectional graphs along the crosshairs). The various displays are chosen using the corresponding icons at the bottom of the panel. Convenient Print Screen controls are located the 2D and 3D displays and allow the user to save an image of the current view in BMP format.

HOME and SETUP TABS

The right-hand side of the software contains the Home and Setup tabs. The Home tab allows the user to select the type of measurements performed (like 4-sigma and FWHM). It also shows the resulting measures of the beam. The Setup tab contains all the measurement parameters, like Exposure Time, Image Orientation, Averaging, Active Area definition (ROI) and more.

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MONITORS

ENERGY DETECTORS

POWER DETECTORS

HIGH POWER DETECTORS

PHOTO DETECTORS

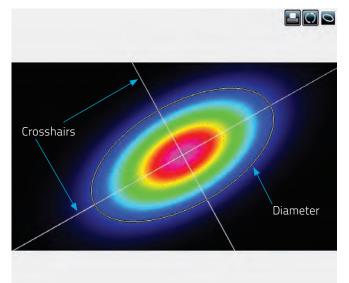
THZ DETECTORS

OEM DETECTORS

SPECIAL PRODUCTS

BEAMAGE-3.0

2D, 3D AND XY DISPLAYS



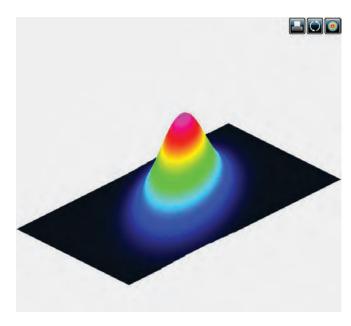
2D DISPLAY

The 2D display features the crosshairs (set to the major and minor axis or along specified angles) and the measured diameter of the beam. This diameter varies with the chosen definition (4-sigma, FWHM, 1/e², etc.) and its display can be turned ON or OFF. The Print Screen button allows to save a picture of the current screen in BMP format.

Print Screen

 \bigcirc **Reset View**





XY DISPLAY

The XY display plots cross-sectional graphs of the beam along the crosshairs. This display features many useful tools, like zoom, cursor, and FWHM and 1/e² level bars. It is also possible to display the graphs in semi-log format to enhance the details in the low intensity parts of the beam.

| 📄 Save Data | 🔎 Zoom | 📐 Gauss |
|-------------|-----------|---------|
| Semi-Log | Show/Hide | Show |
| Graph | Cursor | FWH |

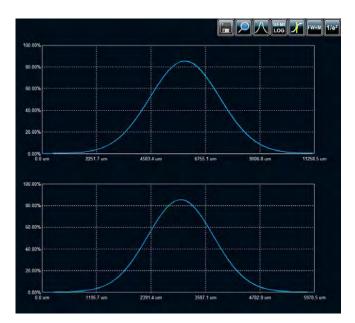
3D DISPLAY

The 3D display shows the actual shape of the beam. It is possible to easily zoom, pan and rotate the data. The very useful Reset button allows to put the data back in its original configuration. This display also features a Print Screen button to save the latest image in BMP format.



🔘 Reset View







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BEAMAGE-3.0

MAIN FUNCTIONS

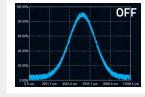


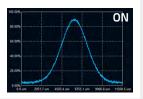
SUBTRACT BACKGROUND

The background subtraction function is a necessary tool to have an accurate measurement and to abide by the ISO-11146-3:2004 standards. By taking 10 images and averaging them pixel by pixel to compute the average background map, contamination of all images can be avoided with the help of environment noise subtraction.

FILTER

Filter out the noise in your beam profile by using this spatial filter function. This tool is great for low quality lasers or low level signals.





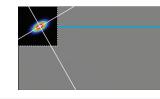
TRIGGER

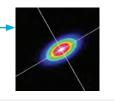
For the case of pulsed laser sources, the trigger function will be useful to synchronize the system's capture rate with the source's repetition rate, especially when this one is low (<16 Hz). To be achieved, a TTL (0-5 V) or other (1.1-24 V) trigger signal can be connected to the Beamage-3.0 camera via a BNC or SMA plug.



ACTIVE AREA (ROI)

Increase the data transfer rate by reducing the area of the sensor that is scanned. This tool is perfect for small beams that don't need the full sensor area.







ANIMATE

Give life to your measures with the animate function. With as much as 32 frame images temporarily saved in the buffer, simply pressing the animation button will create a movie with any display (2D, 3D and XY). This allows to visualize the beam while working offline and have a recalculation process if the beam diameter definition or crosshair parameters are changed.



NORMALIZE

The normalize function spreads the intensity over the full range (0% to 100%). This is especially useful with low level signals or to enhance the variations in the beam.

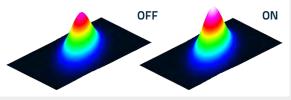




IMAGE AVERAGING

The image averaging function uses a temporal filter to provide the possibility to take 2, 5 or as much as 10 images of the beam to create a single timeaveraged image with them. This process will smooth the beam fluctuations that can occur over time when working with unstable laser sources.



PIXEL ADDRESSING

Increase the data tranfer rate by using larger pixels or by reducing the number of pixels. This is great for large beams that don't need the full resolution.



BEAM DIAGNOSTICS

MONITORS

THZ DETECTORS

DEM DETECTORS

BEAMAGE-3.0

CHOOSING THE CORRECT BEAM DIAMETER DEFINITION

Since Gaussians are infinitely large, borders have to be defined for the validity of calculation. To suit all types of requirements, the Beamage-3.0 software offers 4 different definitions for the beam diameter (d_o) measurement. The first 3 definitions are appropriated for elliptical and circular profiles and the last one is for circular profiles only:

- ▶ 4 sigma (ISO): The beam diameter definition is set by default to 4 sigma because it conforms to the ISO 11146-1:2005¹ and ISO 11146-2:2005² standards. With this definition, the computation time is raised and thus the frame rate is reduced because almost the entire image (4 times the curve standard deviation) is used to compute the beam parameters.
- 1/e2 along crosshairs (13.5%): This definition is similar to 4 sigma but allows a faster frame rate. With this definition, the Gaussians are cut where the energy or intensity reaches 13,5 % of the peak value. Users can use this definition to increase the frame rate and still have a good approximation of the diameter of their elliptical beam.
- **FWHM along crosshairs (50%):** This definition is also faster than 4 sigma and works in a similar fashion as 1/e2 along crosshairs, but clips the beam at 50% of the peak value.
- 86% effective diameter (D86): This beam definition is designed for circular (or almost circular) profiles only. It computes the diameter of a circular beam containing 86% of the total energy or intensity. Since the software assumes the beam is cicular, it does not calculate the major and minor axes, nor the orientation and ellipticity, which makes D86 the fastest measurement mode.

BEAM CENTROID, ELLIPTICITY AND ORIENTATION (ISO 11146:2005^{1,2} COMPLIANCE)

The **beam centroid** (center of energy) coordinates for both X and Y axes are given by these equations, which are weighted means for energy:

$$\overline{\mathbf{x}} = \frac{\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \mathsf{E}(\mathbf{x}, \mathbf{y}, \mathbf{z}) \mathbf{x} d\mathbf{x} d\mathbf{y}}{\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \mathsf{E}(\mathbf{x}, \mathbf{y}, \mathbf{z}) d\mathbf{x} d\mathbf{y}} \qquad \qquad \overline{\mathbf{y}} = \frac{\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \mathsf{E}(\mathbf{x}, \mathbf{y}, \mathbf{z}) \mathbf{y} d\mathbf{x} d\mathbf{y}}{\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \mathsf{E}(\mathbf{x}, \mathbf{y}, \mathbf{z}) d\mathbf{x} d\mathbf{y}}$$

The **ellipticity**, which can take a value between 0% and 100%, is defined as the ratio between the shorter (minor axis) and longer (major axis) widths. Evidently, a perfectly circular beam will have an ellipticity of 100%.

The **beam orientation**, which can take a value from -45° to 45°, is defined as the angle between the X axis of the sensor and the beam axis (either minor or major, whichever is closest).

GAUSSIAN FIT AND ROUGHNESS FIT

According to the ISO 13694:2000³ standards, the roughness fit factor, which is an indicator of the maximum deviation between the theoretical Gaussian curve and the measured one, takes a value between 0% and 100% and is given by this equation:

Roughness Fit (%) =
$$\left[\frac{\left|E_{i} - E_{i}^{a}\right|_{max}}{E_{max}}\right] \times 100\%$$

E is the measured curve and E^a the theoretical one. The closer to 0% the better is the roughness fit.

The Gaussian fit factor, on the other hand, indicates how the experimental curve is close to a theoretical Gaussian. It can take a value between 0% and 100% and is given by this equation:

Gaussian Fit (%) =
$$\begin{bmatrix} 1 - \frac{\sum \left| \mathsf{E}_{i} - \mathsf{E}_{i}^{a} \right|}{\sum \mathsf{E}_{i}^{a}} \end{bmatrix} \times 100\%$$

E is the measured curve and E^a the theoretical one. The closer to 100% the better is the Gaussian fit.

2. ISO 11146-2:2005 : applicable to general astigmatic beams or unknown types of beams. Within this standard, the description of laser beams is done with the second order moments of the Wigner distribution. Relevant physical quantities such as beam widths can be calculated from them. 3. ISO 13694:2000 : test methods for laser beam power (energy) density distribution.

Catalogue 2013_V2.0

BEAM DIAGNOSTICS

SPECIAL PRODUCTS

MONITORS

^{1.} ISO 11146-1:2005 : methods for measuring beam width, among others, only applicable for stigmatic and simple astigmatic beams.

Real-Time M² Module for Beamage-3.0

BEAMAGE-M2

0

9

0

BEAM DIAGNOSTICS



Stand with Steel Post (Model Number: 201102)

AVAILABLE MODEL

Beamage-M2



gentec.e.

BSC-190, BSC-350, VA-0-93 Beam Splitters and Attenuators



Coming in fall 2013

KEY FEATURES

1 Instant Measurement

Innovative technology The Fabry-Perot optics allow the M2 factor measurement in less than a second with *no moving parts*

2 ISO Compliant

All the calculations are ISO 11136 and 13694 compliant

3 Built–In Attenuation

OD4 attenuation provided by the Fabry-Perot optics itself and optional removable attenuators are available for attenuation up to OD7

4 Passive Device

No external power source needed to operate the M² Module

5 Modular

The Beamage-3.0 camera profiler can be used separately from the M² module for needs of spatial intensity or energy profiling

6 Versatile

The compact design makes it suitable for a wide range of scientific, medical and industrial applications

- 7 Complete Software Easy-to-use software with an array of useful functions and tools
- 8 Compact Assembly Can be inserted almost anywhere in optical systems for accurate troubleshooting

SEE ALSO

| ACCESSORIES FOR BEAM DIAGNOSTICS | 186 |
|----------------------------------|-----|
| LIST OF REGULAR ACCESSORIES | 188 |





MONITORS

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31.6

BEAMAGE-M2

Real-Time M², Divergence and Waist

Real-Time ISO Compliant measurement with no moving parts

50 µm - 6 mm

Easy setup and alignement System can be calibrated and ready to go within minutes

190 - 1100 nm a

MEASUREMENT CHARACTERISTICS

SPECIFICATIONS

BEAMAGE-M2

M² Measurement **Rayleigh Range** Setup & Alignment

MEASUREMENTS

SETUP

MODEL

Wavelength Range

Minimum Focal Length Built-In Attenuation (Included)

Additional Built-In Attenuation

PHYSICAL CHARACTERISTICS

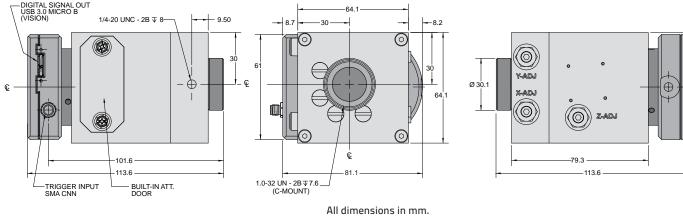
Dimensions (Module only) Dimensions (With Beamage-3.0) Weight (Module only) **Operating Temperature Range Operating Relative Humidity**

ORDERING INFORMATION

Full Product Name Product Number (Stand not included)

a. Limited by the spectral range of the camera.

TECHNICAL DRAWING



Beamage-3.0 camera not included.

Specifications are subject to change without notice

gentec-c.)

Beamage-M2 202302

(covered by interchangeable sets of optics) 100 mm Fabry-Perot Reflective Glasses: OD4 Built-in Attenuation: OD2 (user changeable) Choice of OD1 to OD3

> 64.1H x 77.3W x 97.6D mm 64.1H x 81.1W x 113.6D mm 535 g 10°C - 30°C 5% - 80%

BEAMAGE-M2

THE FABRY-PEROT INTERFEROMETER

To achieve measurements, the system uses a completely passive optical approach. Inside the device, a Fabry-Perot interferometer made with a pair of partially reflective glasses is positioned in front of the sensor of the Beamage-3.0 camera with a convenient angle for the light to oscillate, thus creating time delayed slices. After these slices have landed on the sensor, each one a spatial cross section along the waist, the software simultaneously tracks and analyzes them for unparalleled speed of M² calculation.

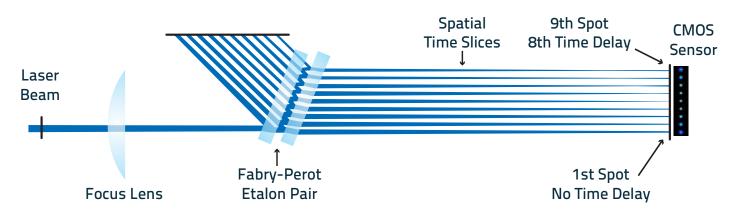
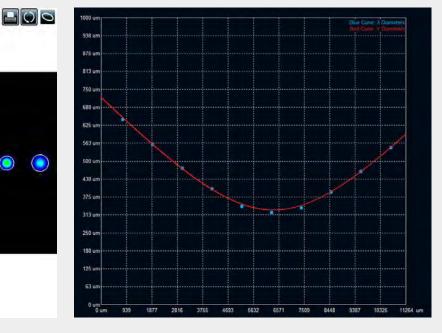


Figure 1. Schematic of the Fabry-Perot optics with time-delayed slices of the beam

INTUITIVE SOFTWARE

The M² measurements are taken directly in our PC-Beamage-3.0 software. An easy step-by-step procedure is clearly indicated directly in the software and allows the user to get the fastest M² measurement available. The ISO calculations give M² values in both the X and Y axes. Thanks to the module having no moving parts and the lightweight software, the M² measures are taken at a rate of 3 fps. The system also automatically detects the multiple beams, allowing for an easy setup. Once the system is calibrated, you can take as many measurements as you like, without moving any parts or modifying parameters.

| | ۲ | ۲ | 0 | ۲ | ۲ | 0 | |
|--|---|---|---|---|---|---|--|
| | | | | | | | |
| | | | | | | | |
| | | | | | | | |



BEAM DIAGNOSTICS

MONITORS

PHOTO DETECTORS

THZ DETECTORS

BEAMAGE-M2



BUILT-IN ATTENUATION

For a large range of powers to be covered and to avoid saturation of the CMOS sensor, the system is equipped with all the necessary built-in attenuation modules. For a focused beam entering the system aperture, the Fabry-Perot interferometer itself first provides an OD4 attenuation (ten thousand times). If this is still not sufficient, attenuators can be inserted in a removeable compartment located between the Fabry-Perot pair and the CMOS sensor. This provides an optional attenuation up to OD3 (thousand times), for a total attenuation up to OD7 (ten million times). In the case that a greater attenuation is necessary to avoid overheating of the optics, additional partially reflective glasses can be easily mounted on the C-mount aperture of the device.

ISO COMPLIANT M² FACTOR

The M² factor can be considered as a qualitative indicator of beam quality. In other words, it is an indicator of closeness to an ideal Gaussian beam at the same wavelength in terms of propagation. It can be defined as the ratio between the beam parameter product (beam waist multiplied by divergence) of the measured experimental beam and the one of the ideal Gaussian beam. Since the ideal Gaussian beam diverges more slowly than any other shape, the M² is always greater or equal to one. An M² very close to 1 indicates an excellent beam quality. To conform to the ISO 11146 and 13694 standards, the software uses the second order spatial moments to compute the M² factor. All the calculations are ISO compliant.

FOCAL LENGTHS

For the measurement of the propagation parameters of a laser beam, the latter must be focused through a convergent lens. This creates the optical far-field, where the divergence is constant at the focus spot of the lens. The adjustable distance between the Fabry-Perot etalons allows the measurement of beam propagation parameters for a large range of focal lengths. Measurement is possible for any system that uses a lens of focal length equal or higher than 100 mm.

REAL-TIME MONITORING AND MODULARITY

Unlike other M² measurement systems, the Beamage-M2 can measure the beam propagation parameters of a laser beam without the need of moving parts, providing calculation of the M² factor in less than a second. This condition allows the possibility to do on-line monitoring. By establishing limit values and monitoring the M² factor to keep it within acceptable range, it is possible to perform fast troubleshooting to ensure that the laser is doing its job correctly and to maintain the control and reliability of a process. Its modular design allows users who only want to measure the energy or intensity spatial profile to remove the Beamage-3.0 from the M² module and use it separately as a beam profiler.



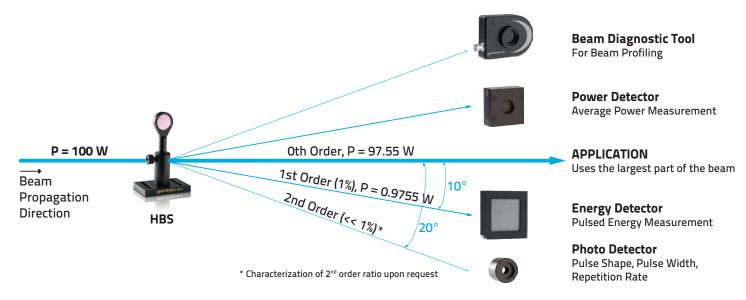
DIFFRACTIVE OPTICS

OVERVIEW

What if you need to measure the performance of the beam in real-time while your application is online? You cannot insert or remove optical components or interrupt the beam either. How do you do that? One way is to divert a small fraction of the beam that is an exact replica of the main beam. Sampling is also a solution if the beam is too 'hot" for your diagnostic instruments to handle. In either case, almost all of the main beam is available to do its job.

Figure 1. Example HBS Application

Pulsed ND:YAG, 1064 nm, 1J @ 100 Hz (100 W)



SAMPLING

One approach is to use something like a moveable mirror to sample in time. The beam is interrupted and diverted for small slices of time. A big disadvantage though is that the time sampler provides average values so it is not well suited for real-time operation, especially with pulsed lasers. The other way is to continuously divert a tiny fraction of the beam to another angle while the main beam passes through, along its original line. However it is done, the sample needs to be a low power replica of the main beam.

REAL-TIME BEAM SAMPLING

The components or methods suitable for real-time beam sampling are summarized in Table 1. The particular requirements of an application will narrow down the list of acceptable methods. All of these methods provide a decent replica of the main beam in the sampled beam and all can withstand reasonably high power. If it is important that the polarization of the sample be the same as the beam, then the Mirror and the Frustrated Total Internal Reflection are not good choices due to mixing of the horizontal and vertical polarizations. Low sampling fraction is very good. This means that most of the beam passes on to the application with a tiny percentage being diverted. The Mirror and Hole Matrix remove much more energy from the beam than the other components which is a problem for many applications.

DIFFRACTIVE OPTICS

ISSUES IN BEAM SAMPLING

Table 1. Comparison of Real-Time Sampling Methods

| Table 1. Comparison of Real-Time Sampling Methods | Spatial Profile Available | Polarization Insensitive | Low Sampling Fraction | Sustain High Power | V bration Insensitive | Environment Insensitive | Cartesian Main Beam | Small Unusable Losses | Commercial Product Available |
|--|------------------------------|-----------------------------|--------------------------|-----------------------|--------------------------|----------------------------|------------------------|--------------------------|---------------------------------|
| Reflective Samplers | | | | | | | | | |
| Wedge: Low-Reflective dielectric coatings on both faces (Rmin) | ✓ | 1 | ✓ | ✓ | | | | ✓ | v |
| Mirror: Leakage from high reflectivity mirror (Rmax) | v | | | ✓ | ✓ | | ✓ | v | v |
| Refractive Samplers | | | | | | | | | |
| Cascaded Wedges | v | √ | ✓ | √ | | √ | | | |
| Frustrated Total Internal Reflection (FTIR): Adjustable gap between two prisms | 1 | | ✓ | ✓ | | | ✓ | ✓ | |
| Transmission Samplers | | | | | | | | | |
| Hole matrix: Periodic array of holes machined in highly reflective mirror or transparent substrate | v | √ | | ✓ | ✓ | | ✓ | √ | |
| Holographic: Relief hologram etched on transparent substrate | v | v | ✓ | v | ✓ | ✓ | ✓ | ✓ | v |

ENVIRONMENTAL ISSUES

If the relative position of the beam on the sampler is critical, vibration will have a disruptive effect. The methods employing refraction to some degree (eg. prisms and wedges) are highly sensitive to vibration. This includes vibration in the beam as well as the sampler. You will prefer other choices in rough environments or for laser beams that do not have great pointing stability. Changing temperature and humidity can be a problem for all but the Holographic sampler and Cascaded Wedges. This is an important consideration for industrial environments.

APPLICATION ISSUES

Cartesian main beam: if it is important that the main beam continue either parallel or perpendicular to the incident beam, you would have to rule out the Cascaded Wedges or the Wedge. The need for that depends on the design of the optical train. The other problem for the Cascaded Wedges is its unusable losses. Compared to the other methods, a significant fraction of the energy that is diverted from the main beam is not useful for sampling and must be dissipated. That can be substantial in high power applications. From the table you can see that the holographic sampler is suited to the widest range of applications. MONITORS

ENERGY DETECTORS

POWER DETECTORS

HIGH POWER DETECTORS



MONITORS

SPECIAL PRODUCTS

HBS SPECIFICATIONS

| MODELS | STANDARD HBS | CUSTOM CAPABILITIES |
|-----------------------------|--------------------|---------------------|
| 1 ST ORDER RATIO | 0.05 % or 1 % | 0.05 % to 10 % |
| WAVELENGTHS | 355, 532 & 1064 nm | 250 to 2100 nm |
| DIAMETER | 1 inch | Up to 2 inches |

MEASUREMENT CAPABILITY

| Wavelengths | 355, 532 & 1064 nm | 250 to 2100 nm |
|--|-------------------------------|-------------------------------|
| Substrate | | |
| Shape | Slight wedge 1/2° | With or without edge |
| Contour | Flat | Flat |
| Thickness | 1/8″ | Up to 1/4" |
| Diameter ^a | 1" | Up to 2.5" |
| Coatings | V-AR (both sides or uncoated) | V-AR (both sides or uncoated) |
| Type of Grating | Sinusoidal | Sinusoidal or Binary |
| Typical Calibration Accuracy (1 st order) | ±3 % | ±2 % |
| 1 st Order Ratio | Depends on Wavelength | Depends on Wavelength |
| 355 nm | 1 % | 0.2 to 5 % |
| 532 nm | 1 % | 0.05 to 10 % |
| 1064 nm | 1 % and 0.05 % | 0.05 to 10 % |
| 1 st Order Angle | Depends on Wavelength | Depends on Wavelength |
| 355 nm | 10° | Up to 13° |
| 532 nm | 10° | Up to 20° |
| 1064 nm | 10° | Up to 20° |
| Total Insertion Loss (V-AR) | 0.3 % per side (typical) | 0.2 % to 2 % per side |
| Total Insertion Loss (Uncoated) | 4 % per surface | 4 % per surface |
| | | |

DAMAGE THRESHOLDS

| Maximum Energy Density (1064 nm, uncoated) Maximum Power Density (1064 nm, V-AR) | | Up to 86 J/cm²Up to 86 J/cm²Up to 2 MW/cm²Up to 2 MW/cm² | | | | |
|---|------------|--|-----------|----------------------|------------------------|----------------|
| STANDARD HBS MODELS | Wavelenght | 1 st Order Ratio | Coating | Max En. Dens. | Max Power Dens. | Product Number |
| HBS-355-100-1C-10 | 355 nm | 1 % | V-AR 355 | 5 J/cm ² | 0.5 MW/cm ² | 23799 |
| HBS-532-100-1C-10 | 532 nm | 1 % | V-AR 532 | 10 J/cm ² | 1 MW/cm ² | 20731 |
| HBS-532-100-1U-10 | 532 nm | 1 % | None | 58 J/cm ² | N/A | 21262 |
| HBS-1064-100-1C-10 | 1064 nm | 1 % | V-AR 1064 | 20 J/cm ² | 2 MW/cm ² | 20733 |
| HBS-1064-100-1U-10 | 1064 nm | 1 % | None | 86 J/cm ² | N/A | 21263 |
| HBS-1064-2000-1C-10 | 1064 nm | 0.05 % | V-AR 1064 | 20 J/cm ² | 2 MW/cm ² | 23977 |

Specifications are subject to change without notice

a. Clear aperture of the grating is 80% of the surface of the substrate.

BEAM DIAGNOSTICS

MONITORS

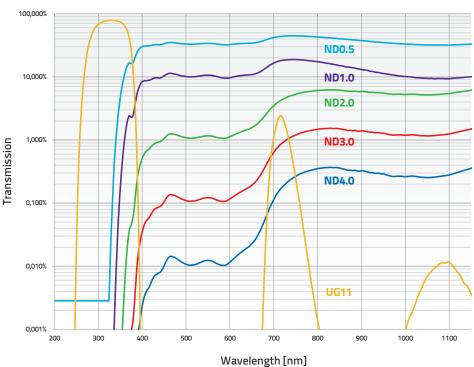
ACCESSORIES FOR BD

ND FILTERS

DESCRIPTION

We offer various Neutral Density filters that are C-Mount threaded and can be stacked directly at the aperture of the camera. Sets of 3 or 5 filters are also available. We also offer a special color glass filter designed for the UV. The UG11-UV filter transmits between 20% and 70%, depending on the wavelength and is useful for applications between 250 nm and 370 nm. Check the parts list on the right for details on all the models available.





| Part # | Description |
|---------|--|
| ND0.5 | T = ~20% |
| ND1.0 | T = ~10% |
| ND2.0 | T = ~1% |
| ND3.0 | T = ~0.1% |
| ND4.0 | T = ~0.01% |
| ND5.0 | T = ~0.001% |
| UG11 | T = ~20 - 70% (from 250 - 370 nm) |
| NDSET-3 | Set of 3 ND filters: ND1.0, ND2.0, ND3.0 |
| NDSET-5 | Set of 5 ND filters: ND1.0, ND2.0, ND3.0, ND4.0, ND5.0 |

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BEAM DIAGNOSTICS

MONITORS

OEM DETECTORS

ACCESSORIES FOR BD

VA-0-93 - VARIABLE ATTENUATOR



DESCRIPTION

The VA-0-93 is a simple-to-use variable attenuator. It consists of a bank of four filter wheels, each with three different filters ranging from 100% transmission down to 0.003 %. This filter bank offers almost continuous attenuation from 0 to more than 93 dB (Optical Density > 9).

The VA-0-93 has three M6 mounting holes and can also connect directly to the C-mount port of a camera. VA-0-93 uses Schott NG absorbing filter glass (NG). The filters have a clear aperture of 18 mm Ø. All filters are mounted at a 4° angle to suppress back-reflection interference fringes.

SPECIFICATIONS

| Maximum Attenuation: | 93 |
|-------------------------|-----|
| Minimum Attenuation: | 0 0 |
| Maximum Power Density: | 11 |
| Maximum Energy Density: | 10 |
| Wavelength Range: | 35 |
| Clear Aperture: | 18 |
| Angle: | 4° |
| Mounting: | 3 : |

3 dB (OD9) dB W/cm² 00 mJ/cm² 50 - 2200 nm 3 mm Ø x M6, C-Mount

| | | | Wheel # | | | | | | | | | |
|--------|---|-----|---------|----|-----|----|-----|----|-------|--|--|--|
| | | 1 | | 2 | | 3 | | 4 | | | | |
| | | dB | % | dB | % | dB | % | dB | % | | | |
| # | 1 | 0 | 100 | 0 | 100 | 0 | 100 | 0 | 100 | | | |
| | 2 | 0.5 | 90 | 5 | 30 | 20 | 1 | 35 | 0.03 | | | |
| Filter | 3 | 1 | 80 | 10 | 10 | 25 | 0.3 | 40 | 0.01 | | | |
| ш | 4 | 3 | 50 | 15 | 3 | 30 | 0.1 | 45 | 0.003 | | | |

BSC-190 & BSC-350 - BEAM SPLITTER CUBES



DESCRIPTION

The BSC beam splitter cube takes a fixed ratio beam sample. It uses the front surface reflection from an uncoated laser mirror to achieve a reflection of 3% to 10% of the main laser beam for further analysis.

The surface is polished to 10-5 scratch-dig and 1/10 wave finish, wedged at 30 arcmin to avoid interference fringes and can take power densities up to 2 GW/cm². Like the VA-0-93 attenuator, it has C-Mount ports and can be connected to the VA-0-93 and your camera with compatible connecting tubes. It can post mount from an M6 threaded post.

SPECIFICATIONS

Attenuation: **Spectral Range:**

BSC-350: BSC-190: **Clear Aperture:** Damage Threshold: 3% to 10% (Polarization dependent)

350 - 2200 nm

190 - 2200 nm

19 mm 50 J/cm²

Part # BSC-350

BSC-190

Description

| Beam Splitter Cube (350 - 2200 nm) |
|-------------------------------------|
| UV Beam Splitter Cube (190 - 2200 n |

HIGH POWER DETECTORS

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nm)